

Theory Of Machines Velocity Analysis

Mechanisms and Mechanical Devices Sourcebook, Fourth Edition
Theory of Machines: Kinematics and Dynamics
Introduction to the Theory of Flow Machines
Advanced Theory of Mechanisms and Machines
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of Crank-Piston Mechanisms THEORY OF MACHINES Theory of Machines

Mechanisms and Mechanical Devices Sourcebook, Fourth Edition

Theory of Machines: Kinematics and Dynamics

This Book Evolved Itself Out Of 25 Years Of Teaching Experience In The Subject, Moulding Different Important Aspects Into A One Year Course Of Mechanism And Machine Theory. Basic Principles Of Analysis And Synthesis Of Mechanisms With Lower And Higher Pairs Are Both Included Considering Both Kinematic And Kinetic Aspects. A Chapter On Hydrodynamic Lubrication Is Included In The Book. Balancing Machines Are Introduced In The Chapter On Balancing Of Rotating Parts. Mechanisms Used In Control Namely, Governors And Gyroscopes Are Discussed In A Separate Chapter. The Book Also Contains A Chapter On Principles Of Theory Of Vibrations As Applied To Machines. A Solution Manual To Problems Given At The End Of Each Chapter Is Also Available. Principles Of Balancing Of Linkages Is Also Included. Thus The Book Takes Into Account All Aspects Of Mechanism And Machine Theory To The Reader Studying A First Course On This Subject. This Book Is Intended For Undergraduate Students Taking Basic Courses In Mechanism And

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Machine Theory. The Practice Of Machines Has Been Initially To Use Inventions And Establishment Of Basic Working Models And Then Generalising The Theory And Hence The Earlier Books Emphasises These Principles. With The Advancement Of Theory Particularly In The Last Two Decades, New Books Come Up With A Stress On Specific Topics. The Book Retains All The Aspects Of Mechanism And Machine Theory In A Unified Manner As Far As Possible For A Two Semester Course At Undergraduate Level Without Recourse To Following Several Text Books And Derive The Benefits Of Basic Principles Recently Advanced In Mechanism And Machine Theory.

Introduction to the Theory of Flow Machines

This book develops the basic content for an introductory course in Mechanism and Machine Theory. The text is clear and simple, supported by more than 350 figures. More than 60 solved exercises have been included to mark the translation of this book from Spanish into English. Topics treated include: dynamic analysis of machines; introduction to vibratory behavior; rotor and piston balanced; critical speed for shafts; gears and train gears; synthesis for planar mechanisms; and kinematic and dynamic analysis for robots. The chapters in relation to kinematics and dynamics for planar mechanisms can be studied with the help of WinMecc software, which allows the reader to study in an easy and intuitive way, but exhaustive at the same time. This computer program analyzes planar mechanisms

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of one-degree of freedom and whatever number of links. The program allows users to build a complex mechanism. They can modify any input data in real time changing values in a numeric way or using the computer mouse to manipulate links and vectors while mechanism is moving and showing the results. This powerful tool does not only show the results in a numeric way by means of tables and diagrams but also in a visual way with scalable vectors and curves.

Advanced Theory of Mechanisms and Machines

The concept of moving machine members during a thermodynamic cycle and the variation of displacements, velocities and accelerations forms the subject of kinematics. The study of forces that make the motion is the subject of kinetics; combining these two subjects leads to dynamics of machinery. When we include the machinery aspects such as links, kinematic chains, and mechanisms to form a given machine we have the subject of Theory of Machines. Usually this subject is introduced as a two-semester course, where kinematics and kinetics are taught simultaneously with thermodynamics or heat engines before progressing to the design of machine members. This book provides the material for first semester of a Theory of Machines- course. This book brings in the machine live onto the screen and explains the theory of machines concepts through animations and introduces how the problems are solved in industry to present a complete history in the shortest possible time rather than using graphical (or analytical) methods. Thus the

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students are introduced to the concepts through visual means which brings industrial applications by the end of the two semester program closer, and equips them better for design courses. The International Federation for promotion of Mechanism and Machine Science (IFToMM) has developed standard nomenclature and notation on Mechanism and Machine Science and this book adopts these standards so that any communication between scientists and in the classrooms across the world can make use of the same terminology. This book adopts HyperWorks MotionSolve to perform the analysis and visualizations, though the book can be used independent of the requirement of any particular software. However, having this software helps in further studies and analysis. The avis can be seen by entering the ISBN of this book at the Springer Extras website at extras.springer.com

Theory of Machines and Mechanisms - II

A planar or two-dimensional (2D) mechanism is the combination of two or more machine elements that are designed to convey a force or motion across parallel planes. For any mechanical engineer, young or old, an understanding of planar mechanism design is fundamental. Mechanical components and complex machines, such as engines or robots, are often designed and conceptualised in 2D before being extended into 3D. Designed to encourage a clear understanding of the nature and design of planar mechanisms, this book favours a frank and

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straightforward approach to teaching the basics of planar mechanism design and the theory of machines with fully worked examples throughout. Key Features: Provides simple instruction in the design and analysis of planar mechanisms, enabling the student to easily navigate the text and find the desired material Covers topics of fundamental importance to mechanical engineering, from planar mechanism kinematics, 2D linkage analyses and 2D linkage design to the fundamentals of spur gears and cam design Shows numerous example solutions using EES (Engineering Equation Solver) and MATLAB software, with appendices dedicated to explaining the use of both computer tools Follows end-of-chapter problems with clearly detailed solutions

Mechanism and Machine Theory

The study of the kinematics and dynamics of machines lies at the very core of a mechanical engineering background. Although tremendous advances have been made in the computational and design tools now available, little has changed in the way the subject is presented, both in the classroom and in professional references. Fundamentals of Kinem

Theory of Machines and Mechanisms I.

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A new approach to the theory of mechanisms and machines, based on a lecture course for mechanical engineering students at the St. Petersburg State Technical University. The material differs from traditional textbooks due to its more profound elaboration of the methods of structural, geometric, kinematic and dynamic analysis. These established and novel methods take into account the needs of modern machine design as well as the potential of computers.

Theory of Machines

The aim of this book is to motivate students into learning Machine Analysis by reinforcing theory and applications throughout the text. The author uses an enthusiastic 'hands-on' approach by including photos of actual mechanisms in place of abstract line illustrations, and directs students towards developing their own software for mechanism analysis using Excel & Matlab. An accompanying website includes a detailed list of tips for learning machine analysis, including tips on working homework problems, note taking, preparing for tests, computer programming and other topics to aid in student success. Study guides for each chapter that focus on teaching the thought process needed to solve problems by presenting practice problems are included, as are computer animations for common mechanisms discussed in the text.

New Advances in Mechanism and Machine Science

Theory of Machines

This up-to-date introduction to kinematic analysis ensures relevance by using actual machines and mechanisms throughout. *MACHINES & MECHANISMS, 4/e* provides the techniques necessary to study the motion of machines while emphasizing the application of kinematic theories to real-world problems. State-of-the-art techniques and tools are utilized, and analytical techniques are presented without complex mathematics. Reflecting instructor and student feedback, this Fourth Edition's extensive improvements include: a new section introducing special-purpose mechanisms; expanded descriptions of kinematic properties; clearer identification of vector quantities through standard boldface notation; new timing charts; analytical synthesis methods; and more. All end-of-chapter problems have been reviewed, and many new problems have been added.

Fundamentals of Machine Theory and Mechanisms

Does a machine run well by virtue of its accuracies, or its freedoms? This work presents an exciting, diagrammatic display of the hidden geometry of freedom and

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constraint. It bolsters the imaginative design of robots, but applies across all fields of machinery. The figures and their captions comprise alone a self-standing story, and this connects effectively with the rigorously argued text. The seamless combination of the two volumes (1984, 1990) renders the internal cross-referencing (forward and backward within the volumes) easier to look up. The appearance of this paperback is a clear testament to the work's ongoing readership. The term screw theory occurs throughout. This relates (after Ball) to the book's philosophy; and one might equally mention kinetostatics (after Federhofer). An all-pervading, counter-intuitive fact accordingly presents itself: while, analogously, angular velocity relates to force, linear velocity relates to couple. A direct consequence of Freedom in Machinery is a more recent book by the same author. Specifically titled General Spatial Involute Gearing and published in Germany (2003), it exemplifies the many ways in which Freedom in Machinery clarifies the enigmatic field of spatial mechanism. That field continuously expands with the current, continuous thrust of ordinary engineering practice.

Mechanical Design Handbook, Second Edition

Theory of Machines

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The third edition of Theory of Machines: Kinematics and Dynamics comprehensively covers theory of machines for undergraduate students of Mechanical and Civil Engineering. The main objective of the book is to present the concepts in a logical, innovative and lucid manner with easy to understand illustrations and diagrams; the book is a treasure in itself for Mechanical Engineers.

Kinematic Analysis of Mechanisms

The Theory of Machines is an important subject to mechanical engineering students of both bachelor's and diploma level. One has to understand the basics of kinematics and dynamics of machines before designing and manufacturing any component. The subject material is presented in such a way that an average student can easily understand the concepts. The graphical methods of analysis are given preference over analytical wherever possible though they lack in accuracy but can be performed quickly. Particular care has been taken to draw diagrams to scale correctly. The results are compared with analytical ones wherever possible. Common doubts that the students have while preparing for the examinations or new faculty in the classrooms have been kept in mind. The same examples are being explained wherever different methods are there instead of giving different examples. The effect of the different parameters on the end result also is shown in the same problem, for example, in cams and governors etc. In the exercises at the end of each chapter, questions from the question papers of various universities are

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given under three categories ? short answer questions, problems, multiple choice questions. Some of the questions may be seen repeated. One should note that they are being given repeatedly and are important for examination purpose.

A Text Book of Theory of Machines

Provides the techniques necessary to study the motion of machines, and emphasizes the application of kinematic theories to real-world machines consistent with the philosophy of engineering and technology programs. This book intends to bridge the gap between a theoretical study of kinematics and the application to practical mechanism.

Design and Analysis of Mechanisms

Theory of Machines is a comprehensive textbook for undergraduate students in Mechanical, Production, Aeronautical, Civil, Chemical and Metallurgical Engineering. It provides a clear exposition of the basic principles and reinforces the development of problem-solving skills with graded end-of-chapter problems. The book has been thoroughly updated and revised with fresh examples and exercises to conform to the syllabi requirements of the universities across the country. The book features an introduction and chapter outline for each chapter; it contains 265

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multiple choice questions at the end of the book; over 300 end-of-chapter exercises; over 150 solved examples interspersed throughout the text and a glossary for ready reference to the terminology.

Theory of Machines and Mechanisms

Totally redesigned to meet the challenges of a new mechanical engineering age, this classic handbook provides a practical overview of the complex issues associated with the design and control of mechanical systems.

Kinematic Chains and Machine Components Design

Kinematics, Dynamics, and Design of Machinery, Third Edition, presents a fresh approach to kinematic design and analysis and is an ideal textbook for senior undergraduates and graduates in mechanical, automotive and production engineering Presents the traditional approach to the design and analysis of kinematic problems and shows how GCP can be used to solve the same problems more simply Provides a new and simpler approach to cam design Includes an increased number of exercise problems Accompanied by a website hosting a solutions manual, teaching slides and MATLAB® programs

Kinematics, Dynamics, and Design of Machinery

Introduction to the Theory of Flow Machines details the fundamental processes and the relations that have a significant influence in the operating mechanism of flow machines. The book first covers the general consideration in flow machines, such as pressure, stress, and cavitation. In the second chapter, the text deals with ducts; this chapter discusses the general remarks, types of flow, and mixing process. Next, the book tackles the types of cascades, along with its concerns. The closing chapter covers the flow machine and its components, such as turbine, wheels, engines, and propellers. The text will be of great use to mechanical engineers and technicians.

Theory of Machines

Machines and Mechanisms

The second edition of Shigley-Uicker maintains the tradition of being very complete, thorough, and somewhat theoretical. The principal changes include an expansion and updating of the dynamics material, expansion of the chapter on gears, an expansion of the material on mechanisms, a new introductory chapter.

Intended for the Kinematics and Dynamics course in Mechanical Engineering departments.

Machine Analysis with Computer Applications for Mechanical Engineers

This volume presents the proceedings of the 12th IFToMM International Symposium on Science of Mechanisms and Machines (SYROM 2017), that was held in "Gheorghe Asachi" Technical University of Iasi, Romania, November 02-03, 2017. It contains applications of mechanisms in several modern technical fields such as mechatronics and robotics, biomechanics, machines and apparatus. The book presents original high-quality contributions on topics related to mechanisms within aspects of theory, design, practice and applications in engineering, including but not limited to: theoretical kinematics, computational kinematics, mechanism design, experimental mechanics, mechanics of robots, dynamics of machinery, dynamics of multi-body systems, control issues of mechanical systems, mechanisms for biomechanics, novel designs, mechanical transmissions, linkages and manipulators, micro-mechanisms, teaching methods, history of mechanism science, industrial and non-industrial applications. In connection with these fields, the book combines the theoretical results with experimental tests.

Machines and Mechanisms

Mechanisms and Machines: Kinematics, Dynamics, and Synthesis

Kinematics of Machinery Through HyperWorks

MECHANISMS AND MACHINES: KINEMATICS, DYNAMICS, AND SYNTHESIS has been designed to serve as a core textbook for the mechanisms and machines course, targeting junior level mechanical engineering students. The book is written with the aim of providing a complete, yet concise, text that can be covered in a single-semester course. The primary goal of the text is to introduce students to the synthesis and analysis of planar mechanisms and machines, using a method well suited to computer programming, known as the Vector Loop Method. Author Michael Stanisic's approach of teaching synthesis first, and then going into analysis, will enable students to actually grasp the mathematics behind mechanism design. The book uses the vector loop method and kinematic coefficients throughout the text, and exhibits a seamless continuity in presentation that is a rare find in engineering texts. The multitude of examples in the book

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cover a large variety of problems and delineate an excellent problem solving methodology. Important Notice: Media content referenced within the product description or the product text may not be available in the ebook version.

The Theory Of Machines Through Solved Problems

Intended to cater to the needs of undergraduate students in mechanical, production, and industrial engineering disciplines, this book provides a comprehensive coverage of the fundamentals of analysis and synthesis (kinematic and dynamic) of mechanisms and machines. It clearly describes the techniques needed to test the suitability of a mechanical system for a given task and to develop a mechanism or machine according to the given specifications. The text develops, in addition, a strong understanding of the kinematics of mechanisms and discusses various types of mechanisms such as cam-and-follower, gears, gear trains and gyroscope.

Fundamentals of Kinematics and Dynamics of Machines and Mechanisms

This text/reference represents the first balanced treatment of graphical and analytical methods for kinematic analysis and synthesis of linkages (planar and

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spatial) and higher-pair mechanisms (cams and gears) in a single-volume format. A significant amount of excellent German literature in the field that previously was not available in English provides extra insight into the subject. Plenty of solved problems and exercise problems are included to sharpen your skills and demonstrate how theory is put into practice.

Third World Congress on the Theory of Machines and Mechanisms

This book gathers the proceedings of the 15th IFToMM World Congress, which was held in Krakow, Poland, from June 30 to July 4, 2019. Having been organized every four years since 1965, the Congress represents the world's largest scientific event on mechanism and machine science (MMS). The contributions cover an extremely diverse range of topics, including biomechanical engineering, computational kinematics, design methodologies, dynamics of machinery, multibody dynamics, gearing and transmissions, history of MMS, linkage and mechanical controls, robotics and mechatronics, micro-mechanisms, reliability of machines and mechanisms, rotor dynamics, standardization of terminology, sustainable energy systems, transportation machinery, tribology and vibration. Selected by means of a rigorous international peer-review process, they highlight numerous exciting advances and ideas that will spur novel research directions and foster new

multidisciplinary collaborations.

Mechanics of Machines

Mechanics of Machinery describes the analysis of machines, covering both the graphical and analytical methods for examining the kinematics and dynamics of mechanisms with low and high pairs. This text, developed and updated from a version published in 1973, includes analytical analysis for all topics discussed, allowing for the use of math software for fast, precise analysis. The chapters include the following:

- Introduction of various mechanisms—such as four-revolute-pairs chain, double-slider, and compound mechanisms—and their motions and functions, with analytical analysis of each one
- Velocities and accelerations in mechanisms, using graphical and analytical analysis
- Analysis of sliding links using a theory developed by the author, which replaces the Coriolis component and is generally easier to apply
- Discussion of cams, with an emphasis on factors affecting cam design, such as the pressure angle and the radius of curvature
- The geometry and kinematics of a wide range of gears
- Force analysis in mechanisms—namely, static force, friction force, and dynamic force analysis
- Balancing machines, specifically rotating parts and reciprocating parts, as well as in-place balancing using vibration measurements

A reference for both students and professionals in mechanical engineering, this informative text offers a deeper understanding of kinematics and related applications. It also supplies the

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fundamentals to enable readers to apply procedures to problems they may encounter in the future.

Kinematic Analysis and Synthesis of Mechanisms

This work has been selected by scholars as being culturally important and is part of the knowledge base of civilization as we know it. This work is in the public domain in the United States of America, and possibly other nations. Within the United States, you may freely copy and distribute this work, as no entity (individual or corporate) has a copyright on the body of the work. Scholars believe, and we concur, that this work is important enough to be preserved, reproduced, and made generally available to the public. To ensure a quality reading experience, this work has been proofread and republished using a format that seamlessly blends the original graphical elements with text in an easy-to-read typeface. We appreciate your support of the preservation process, and thank you for being an important part of keeping this knowledge alive and relevant.

Freedom in Machinery: Volume 1, Introducing Screw Theory

This text blends traditional introductory physics topics with an emphasis on human applications and an expanded coverage of modern physics topics, such as the

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existence of atoms and the conversion of mass into energy. Topical coverage is combined with the author's lively, conversational writing style, innovative features, the direct and clear manner of presentation, and the emphasis on problem solving and practical applications.

Advances in Mechanism and Machine Science

Intended for machinery, mechanism, and device designers; engineers, technicians; and inventors and students, this fourth edition includes a glossary of machine design and kinematics terms; material on robotics; and information on nanotechnology and mechanisms applications.

College Physics

Kinematic Chains and Machine Components Design covers a broad spectrum of critical machine design topics and helps the reader understand the fundamentals and apply the technologies necessary for successful mechanical design and execution. The inclusion of examples and instructive problems present the reader with a teachable computer-oriented text. Useful analytical techniques provide the practitioner and student with powerful tools for the design of kinematic chains and machine components. Kinematic Chains and Machine Components Design serves

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as a on-volume reference for engineers and students in mechanical engineering with applications for all engineers working in the fields of machine design and robotics. The book contains the fundamental laws and theories of science basic to mechanical engineering including mechanisms, robots and machine components to provide the reader with a thorough understanding of mechanical design. Combines theories of kinematics and behavior of mechanisms with the practical design of robots, machine parts, and machine systems into one comprehensive mechanical design book Offers the method of contour equations for the kinematic analysis of mechanicsl systems and dynamic force analysis Mathematica programs and packages for the analysis of mechanical systems

Theory of Machines

While writing the book,we have continuously kept in mind the examination requirments of the students preparing for U.P.S.C.(Engg. Services)and A.M.I.E.(I)examinations.In order to make this volume more useful for them,complete solutions of their examination papers up to 1975 have also been included.Every care has been taken to make this treatise as self-explanatory as possible.The subject matter has been amply illustrated by incorporating a good number of solved,unsolved and well graded examples of almost every variety.

Mechanics of Machinery

The subject theory of machines forms the basis for understanding the working principles of a machine. The theoretical principles involved in machines have immediate application to practical problems. Designed as a text for the undergraduate students of mechanical engineering, it covers all the basics of mechanism and machine theory in a simple and logical manner. The basic theory presented in the book has been evolved out of simple and readily understood principles. The text begins with the discussion on various types of mechanisms and their working principles. Further it discusses the working of Oldham's coupling, automobiles steering gears, engine pressure indicators, and estimation of velocity and acceleration using relative velocity method, complex algebra method and instantaneous centre method. Types of friction and power transmission by belt drives are also explained in detail. Finally it concludes with cam and follower mechanism. KEY FEATURES : Balanced presentation of the graphical and algebraic approaches Numerous solved and unsolved problems in each chapter Wide coverage of topics as per the latest syllabi of various universities

THEORY OF MECHANISMS AND MACHINES

Emphasising the industrial relevance of the subject matter, this book dispenses

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with conventional inaccurate graphical methods used in kinematics of plane mechanisms, cams and balancing. Instead, general vector approach for both plane and space mechanisms have been presented. Undergraduates, graduates and practising engineers will find this book to be of utmost use.

Theory of Machines

Dynamics of Crank-Piston Mechanisms

The Theory Of Machines Or Mechanism And Machine Theory Is A Basic Subject Taught In Engineering Schools To Mechanical Engineering Students. This Subject Lays The Foundation On Which Mechanical Engineering Design And Practice Rests With. It Is Also A Subject Taught When The Students Have Just Entered Engineering Discipline And Are Yet To Formulate Basics Of Mechanical Engineering. This Subject Needs A Lost Of Practice In Solving Engineering Problems And There Is Currently No Good Book Explaining The Subject Through Solved Problems. This Book Is Written To Fill Such A Void And Help The Students Preparing For Examinations. It Contains In All 336 Solved Problems, Several Illustrations And 138 Additional Problems For Practice. Basic Theory And Background Is Presented, Though It Is Not Like A Full Fledged Text Book In That Sense. This Book Contains 20 Chapters, The

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First One Giving A Historical Background On The Subject. The Second Chapter Deals With Planar Mechanisms Explaining Basic Concepts Of Machines. Kinematic Analysis Is Given In Chapter 3 With Graphical As Well As Analytical Tools. The Synthesis Of Mechanisms Is Given In Chapter 4. Additional Mechanisms And Coupler Curve Theory Is Presented In Chapter 5. Chapter 6 Discusses Various Kinds Of Cams, Their Analysis And Design. Spur Gears, Helical Gears, Worm Gears And Bevel Gears And Gear Trains Are Extensively Dealt With In Chapters 7 To 9. Hydrodynamic Thrust And Journal Bearings (Long And Short Bearings) Are Considered In Chapter 10. Static Forces, Inertia Forces And A Combined Force Analysis Of Machines Is Considered In Chapters 11 To 13. The Turning Moment And Flywheel Design Is Given In Chapter 14. Chapters 15 And 16 Deal With Balancing Of Rotating Parts, Reciprocating Parts And Four Bar Linkages. Force Analysis Of Gears And Cams Is Dealt With In Chapter 17. Chapter 18 Is Concerned With Mechanisms Used In Control, Viz., Governors And Gyroscopes. Chapters 19 And 20 Introduce Basic Concepts Of Machine Vibrations And Critical Speeds Of Machinery. A Special Feature Of This Book Is The Availability Of Three Computer Aided Learning Packages For Planar Mechanisms, Their Analysis And Animation, For Analysis Of Cams With Different Followers And Dynamics Of Reciprocating Machines, Balancing And Flywheel Analysis.

THEORY OF MACHINES

Theory of Machines

This monograph focuses on the dynamical research work on crank-piston mechanisms considering basic and additional motions. In order to have full dynamical analyses of piston machines and their mechanisms, the book studies the crank-piston mechanisms with clearances in kinematic pairs. The tasks are carried out by focusing on friction, wear and impacts in mechanisms, as well as cracks formation in links and elasticity of details, with distributed and concentrated masses. Then, the reliability and durability of the mechanisms of piston machines is applied on oil and gas transportation. The monograph is meant for design specialists. It is also useful for specialists-manufacturers and designers of piston machines, scientists and lecturers, doctoral students.

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